

A brief overview of the approach:

- optimization based
- causal
- sliding window BA
- loop closing not used

Sensor modalities:

stereo + IMU

Time for each sequence:

- indoor_forward_11_snapdragon:
real 0m13,692s

- indoor_forward_12_snapdragon:
real 0m10,357s

- indoor_45_3_snapdragon:
real 0m13,228s

- indoor_45_16_snapdragon:
real 0m7,331s

- outdoor_forward_9_snapdragon:
real 0m17,311s

- outdoor_forward_10_snapdragon:
real 0m21,922s

Exact specifications of the hardware used:

Intel Core i7-8700K CPU @ 3.70GHz

Same set of parameters is used throughout all the sequences:

Yes