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07/04/17 1/3

Christian Forster, Zichao Zhang, Michael Gassner, Manuel Werlberger, Davide Scaramuzza SVO: Semi-Direct Visual Odometry for Monocular and Multi-Camera Systems IEEE Transactions on Robotics, Vol. 33, Issue 2, April 2017

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07/04/17 2/3

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07/04/17 3/3