Christian Brändli, PhD christian@insightness.com 0041 077 430 32 59



FROM EVENT-BASED VISIONS TO REAL SYSTEMS



First International Workshop on Event-based Vision ICRA 2017, June 2^{nd,} Singapore

WHO IS INSIGHTNESS







Christian
Brändli, PhD

Managment
PhD thesis in field
Worked at startup
GetYourGuide
Venture Leader
award



Marc
Osswald, PhD
Product
PhD thesis in field
Training as El. &
Mech. Engineer
Intership ESA



Nathan
Baumli

Algorithms

MSc thesis in field
Employee Nr. 1
Internship ABB



Raphael
Berner, PhD
Chip Design
PhD thesis in field
Worked in industry
Quit job to join
company

TEAM

+ 2 Computer Vision Engineers

+ 1 Drone Engineer

+ 1 Chip Designer

ADVISORS

Prof. Tobi Delbruck Albert Bergemont

BOARD MEMBERS

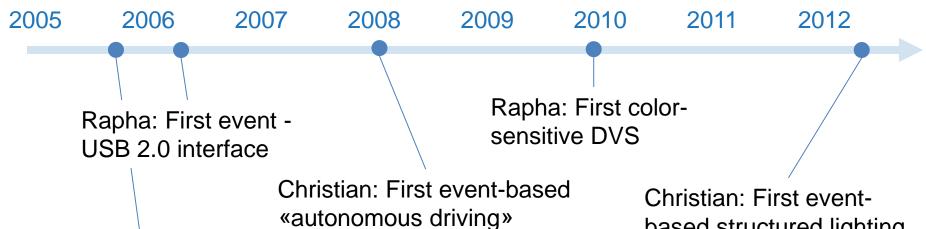
Jim Lewis
Ed Schneider

Co-Founder, expert for event-based vision sensors Ex-VP Maxim Integrated, expert for semiconductors

Serial Entrepreneur (Ex-CEO Mesa, Avalon, ...), Consultant Managing Director, Quan Technology Fund



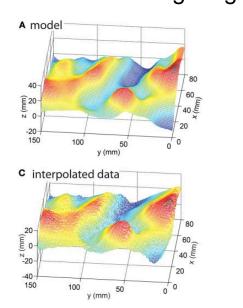
THE HISTORY OF INSIGHTNESS I



Tobi: First working event-based vision sensor (DVS)

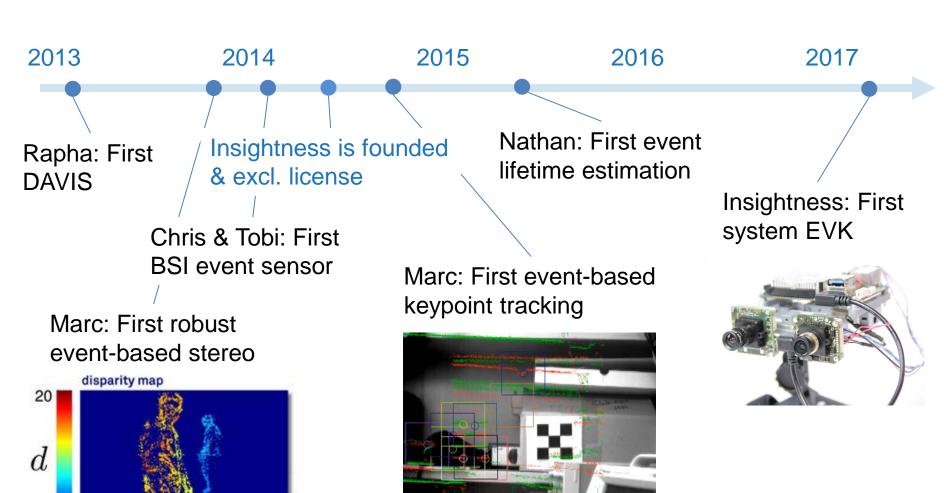


based structured lighting





THE HISTORY OF INSIGHTNESS II





FROM EVENT-BASED VISIONS...

"event-based sensors open frontiers which are unthinkable with standard cameras"

"visual sensing and processing in autonomous vehicles, connected devices, security and surveillance systems"





WHY SYSTEMS?

- There are vision sensors that ...
 - ... are faster
 - ... burn less power
 - ... have more dynamic range
 - ... produce less data
 - ... have more temporal resolution

. . .

The only USP of event-based: EFFICIENCY



EFFICIENCY, A SYSTEM SPEC

- Efficiency is not measured on a sensorlevel but as a system spec
- System: Sensor, processing hardware, algorithms & software
- Making "better" chips or "better" software do not matter if the system they are integrated does not beat state of the art.

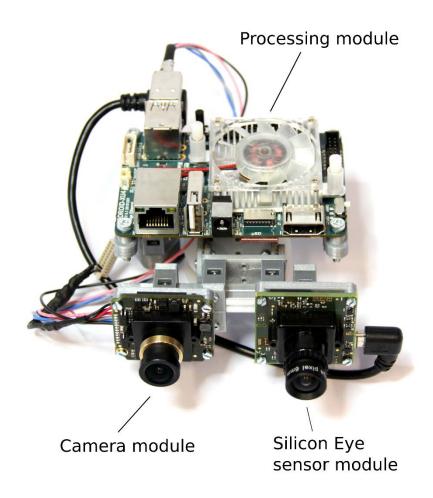


...TO REAL SYSTEMS



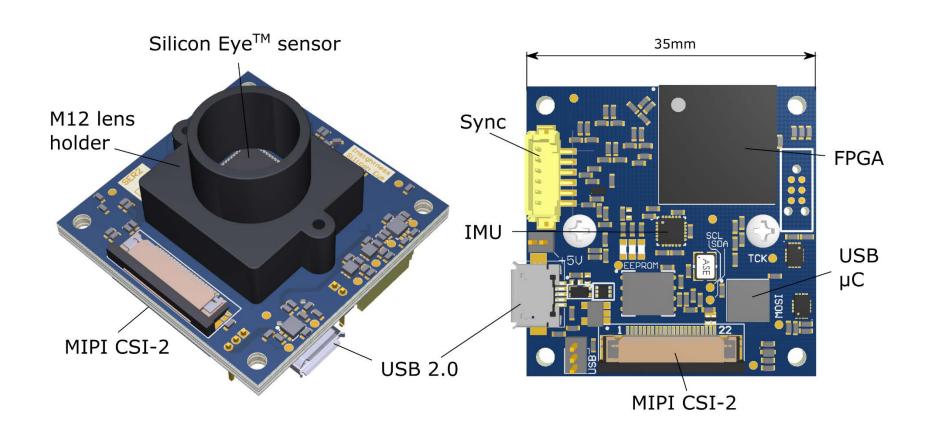


RINO 2 EVALUATION KIT



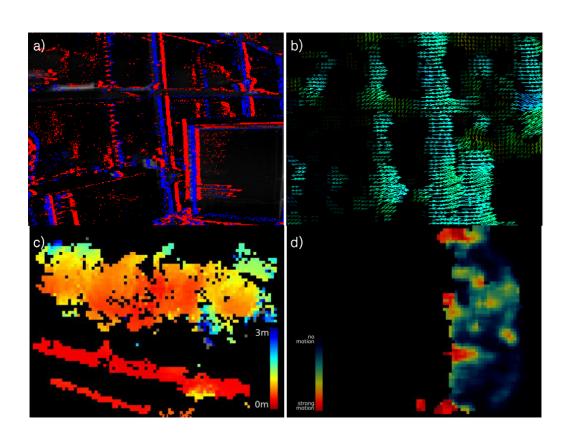


SEES SENSOR MODULE





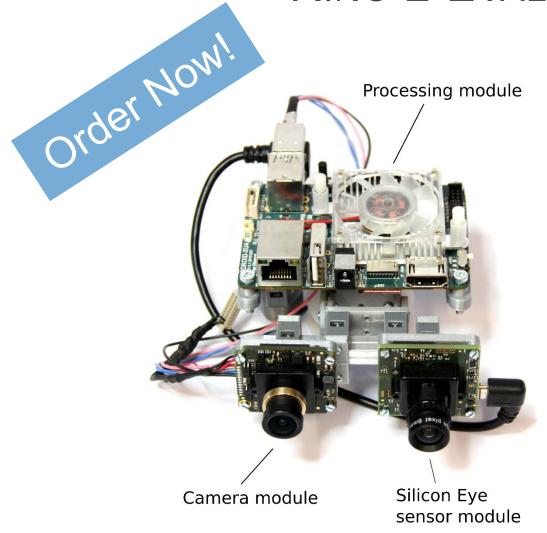
EVK OUTPUT



- Raw DAVIS events (a)
- Raw DAVIS frames
- 9 DoF IMU data
- Raw BlueFox
- Frames
- 6 DoF SVO Pose
- Visual Flow Map (b)
- Depth Map (c)
- Motion Map (d)



RINO 2 EVALUATION KIT





INSIGHTNESS AND YOU

- Apply as Computer Vision Engineer we are hiring!
- Buy our evaluation kit
- Watch and share our youtube video: "Insightness Collision Avoidance"
- Build algorithms and license to us
- Introduce us to companies and investors
- Check out our demo



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